Week7 Recitation

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Outline

Basic Concepts in Object Detection

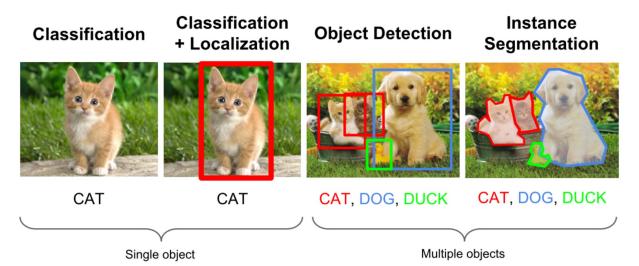
> One algorithm about object detection: R-CNN

Concept

- > The goal of object detection
 - To scan digital images to locate instances of every object, separate them and analyze the necessary features for real-time predictions

Four main tasks in CV

- Classification: classify the category of the object in a image
- Location: locate the position of given object in an image
- Detection: First locate and then classify
- Segmentation: determine which object each pixel belongs to

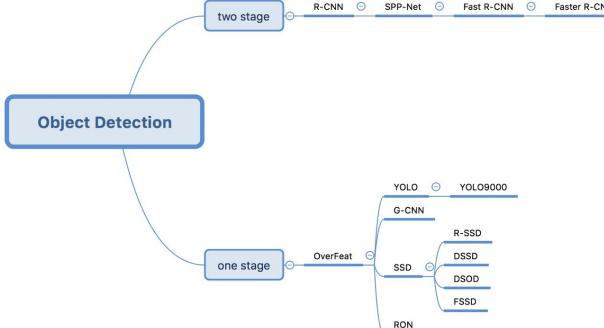


Challenge

- Classification
- > Locate
 - > Object may occur in any position in a image
 - > Object may have different size
 - > Object may have different shape

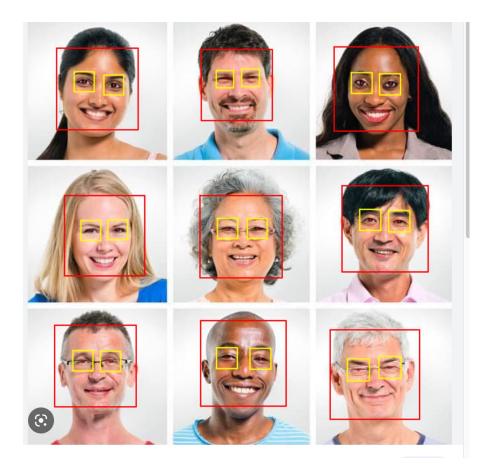
Algorithm

- > Two-stage
 - First region proposal
 - > Then CNN prediction
- > One-stage
 - Directly capture features in an image to simultaneously predict position and label
 Two state of sever and label



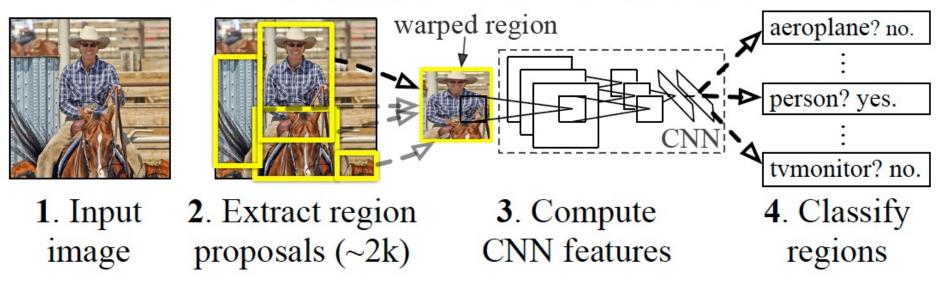
Application

> Face detection, pedestrian detection, vehicle detection, road detection

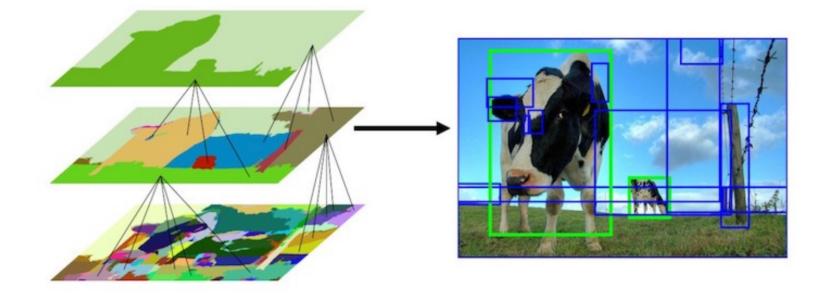


- > The whole system includes three parts
 - The first part generates the category-independent region proposals
 - > The second part is a large convolutional neural network
 - The third module includes a set of SVM which classify the label

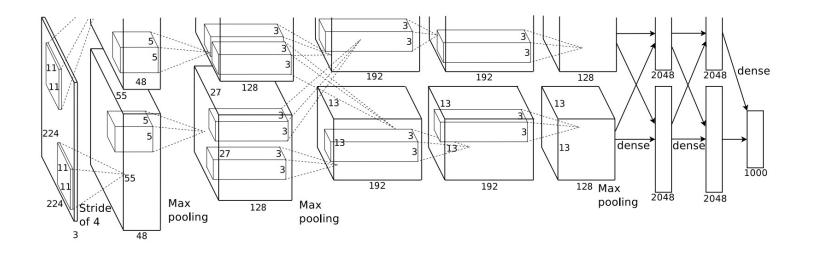
R-CNN: Regions with CNN features



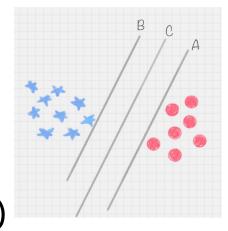
- Region Proposal: Selective Search
 - > Frist, segment an input image
 - > Second, combine the two nearby regions which have high similarity
 - > Third, Go to step 1



- Feature extraction
 - Use a CNN from <u>https://proceedings.neurips.cc/paper/2012/file/c399862d3b9d6b76c8436e924a68c45b-Paper.pdf</u>
 - Five convolutional layers and two fully connected layers to extract features for each region

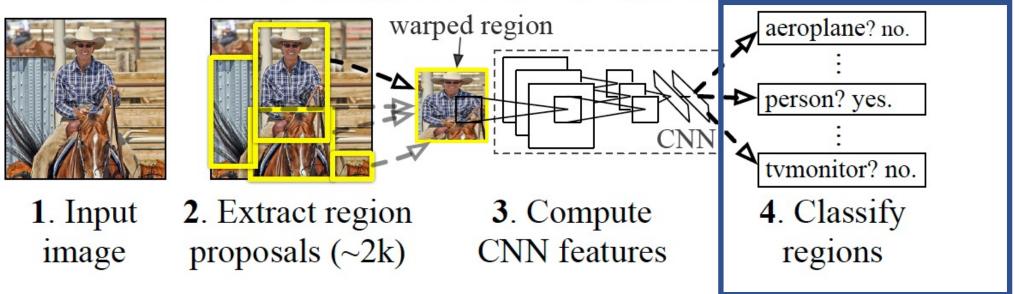


- Region Classification
 - Use a set of SVMs: a binary-classifier (One V.S. Many)



SVM : maximize the minimum distance between support vector and hyper-plane

R-CNN: Regions with CNN features



Any Question?